

Network Coding in a Bluetooth Network

M. Nandhini¹, Dr.K.Nachimuthu²

1. Research Scholar, Department of Computer Science, Jairams Arts and Science College, Karur.
2. Research Advisor, Department of Computer Science, Jairams Arts and Science College, Karur.

Abstract: Bluetooth is widely used today and the devices are cheap and have a low power consumption. Use of Bluetooth in a MANET as well as WSNs is therefore interesting. The overall aggregated bandwidth in a piconet is limited to 768kbps (Basic Data Rate). Using TDD, this bandwidth is shared between the nodes in a piconet based on the fairness algorithm applied. Thus the average bandwidth per node is reduced by the number of nodes transmitting in a piconet. If applying network coding to the piconet makes the communication more efficient, the required number of transmitted packets will decrease. A reduced number of transmitted packets will reduce the radiated power from the node. Furthermore, reduced radiated power will reduce the energy requirement, and increase the lifetime of the battery while maintaining the same bandwidth available. As Bluetooth is primarily used by small battery operated devices, an improved energy budget is welcome.

1. INTRODUCTION

Bluetooth is a short range wireless technology intended to replace cables connecting portable and/or fixed devices [1]. The Bluetooth specification is maintained by the Bluetooth Special Interest Group (SIG). The radio layer is responsible for transmitting and receiving packet of information on the physical channel.

Bluetooth operates in the Industrial Scientific Medical (ISM) band (2.4GHz), and uses 79 channels spaced 1MHz apart from each other [2]. A Bluetooth Security White Paper [3] recommends using long passkey and only pair devices in a secure environment. The computing complexity of generating the initialization key based on the passkey is not large. Using long passkey will increase the work load for an eavesdropper of finding the matching link key. None of the proposed scatternet formation algorithms is fulfilling all of the above requirements. [4] compare some of the proposed algorithms, and evaluate the performance of three of the protocols (Blutrees [5], BlueStars [6] and New Formation protocol [7]) using simulation. Slightly different criteria than the ones above have been emphasized in the comparison. Recent papers propose other algorithms like the Overlaid Bluetooth Piconet and Temporary Scatternet [8] and Enhanced AODV [9]. The first one proposes an interconnection method without scatternet formation, instead interconnecting stand alone piconet. A performance comparison of OBP and Bluetooth Scatternet [10] is made in [11], and conclude a

resiliency to mobility and higher throughput. Low power consumption is emphasized as an

2.THEORETICAL ANALYSIS

Assume a piconet consisting of a master node and two slave nodes as shown in figure 1. The two slave nodes communicate with each other full duplex at equal data rate (symmetrical). According to the TDD scheme of Bluetooth, the master polls the first slave. The slave responds and sends its packet destined for node 2. The master polls the next node, and passes data from the first node to the second node. The second node

important feature in the latter one (EAODV).

responds, and passes its data to the master. This cycle repeats itself until the communication terminates, this protocol is illustrated in Figure 2(a). Assume again the same network topology as previously. Instead of following the previous protocol, the first two polls from the master does not transfer any data but rather send simple poll packets with no payload. The master stores the received data from node 1 and node 2 in a buffer.

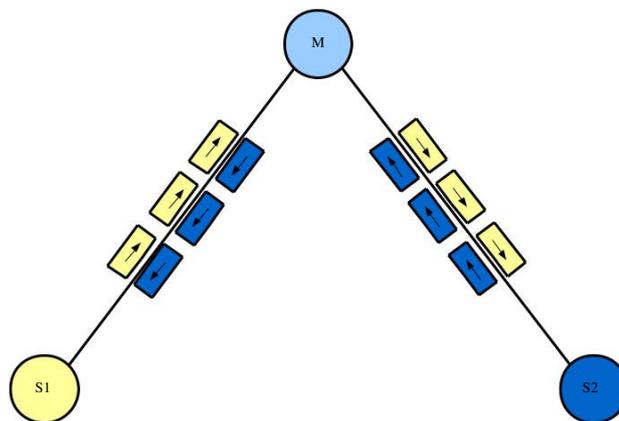
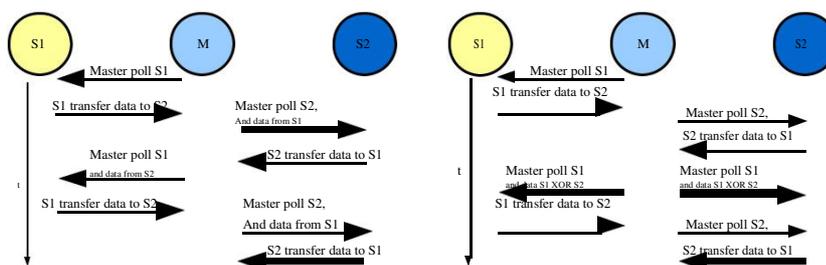


Figure 1: A simple piconet

It then performs combination of the two packets, and sends the encoded packet to both nodes as illustrated in Figure 2(b). This is possible either by using the reserved Active Slave Broadcast address (as carried out in an Emergency Data Delivery System or forcing the receivers to operate in promiscuous mode



(a) Without network coding (b) With network coding

Figure 2: A two slave and one master Bluetooth network

3. THROUGHOUT IMPROVEMENT IN A PICONET BY USING NETWORK CODING

Is it possible to improve the throughput in a piconet using network coding? This section will discuss how this could possible be done, and a protocol for

deterministic network coding in Bluetooth piconet (DNCCBP) is proposed. A network of a master node and four slave nodes. Between the four nodes tra c ows bi-directional and symmetric in pair as shown in Figure .3.

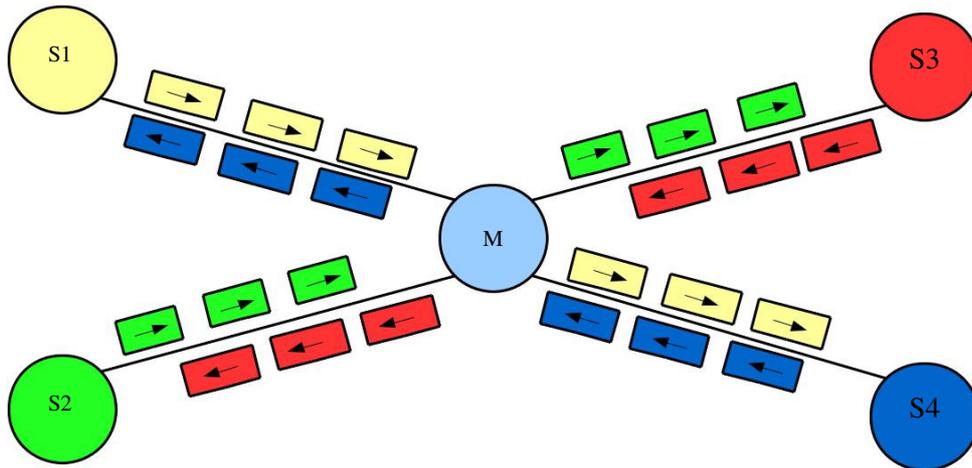


Figure 3: A piconet with four nodes and two bi-directional symmetric communication streams

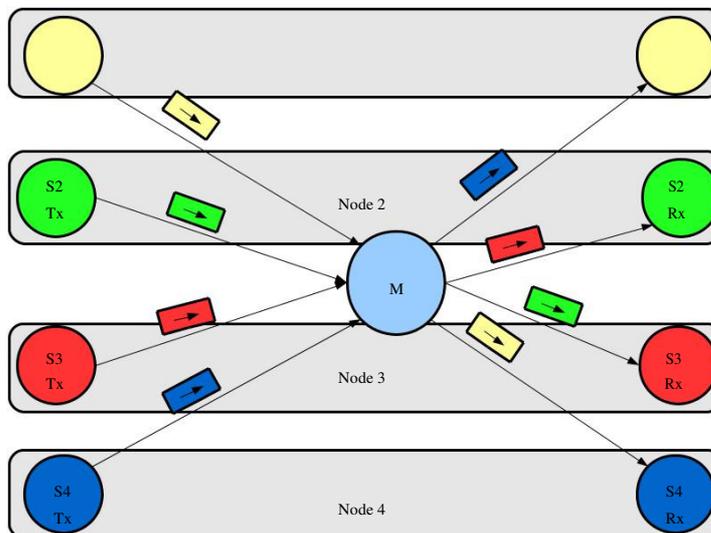


Figure 4: A piconet as a directed graph

Bluetooth frame structure, at every even numbered time slot the master polls a slave. The next time slot data from the polled slave node is transmitted. To explain how to apply network coding, a Bluetooth piconet could be viewed as a directed graph as in Figure.4. On the right hand side of the figure is the transmitting part of the slave nodes (the sources), and the receiving part of the slave nodes (the sinks) is on the left hand side. The master node is in the middle. Figure 5 indicates a

possible distribution and use of time slot in a TDD system. The overall capacity C is divided by the users. Transmission of one packet from one slave to another slave, forwarded by the master is requiring two time slots; one from the source slave to the master, and another time slot from the master to the sink slave. Thus, with n slaves the average capacity per node C_n , is given by $C_n = C/2n$

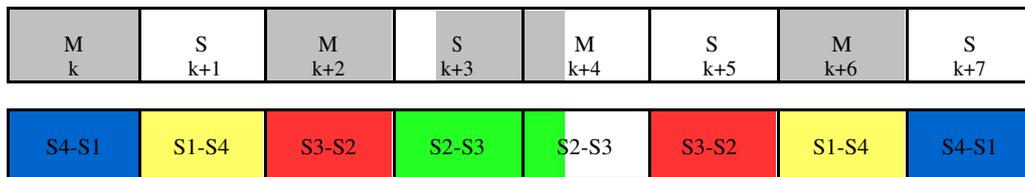


Figure 5: TDMA frame structure

This will reduce the required bandwidth from the master; ergo it is possible to allocate more bandwidth to the slaves. In a Bluetooth network this is done by using DH3/ DH5 or DM3/DM5 in an asynchronous mode. Due to the TDD scheme the master nodes have four periods available.

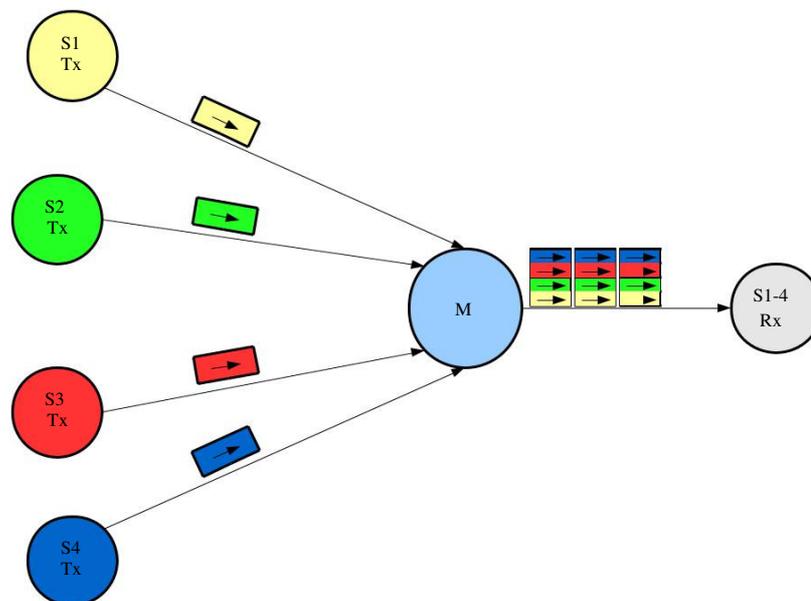


Figure 6: A piconet applying network coding illustrated as a directed graph

By using a synchronous mode, all frames are one time slot long, equally shared among all slaves and the master. Therefore, there will be no throughput improvement using network coding in synchronous mode as the master is required by the TDD protocol to transmit in all four time slots, even though the network coding only requires three.

By increasing the size of the packets a message can consist of three or ve time slots. The empty frame from the master is set to a length of one time slot, and contains only the poll packet. It is possible to, if required, add network coding overhead (e.g. administration such as number of nodes, mapping of nodes to BD ADDR and advertizing a new generation) in this packet. A possible distribution of the TDD scheme could be as shown in Figure 7. The master node saves transmission of 2 or 4 time slots depending on using DH3 or DH5 accordingly.

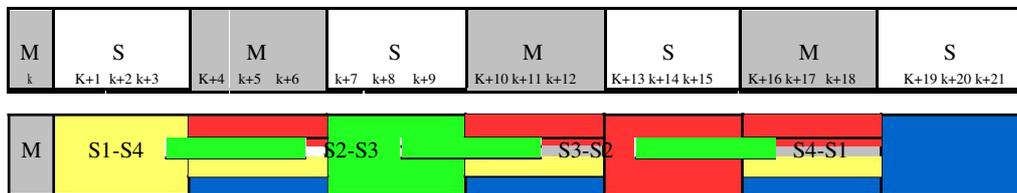


Figure 7: TDMA frame structure in a piconet with network coding

4. THEORETICAL ANALYSIS

In the given example, each unidirectional communication link requires three time slots to transmit the data from slaves to master, and three times three time slots to transmit from the master to the receiving slaves. In total 22 time slots including one poll packet. In general the required number of time slots to transmit a DH3 packet from all source nodes are $3n + 3(n - 1) + 1 = 6n - 2$.

Theorem 1. The average throughput gain, G , using DNCBP-DH3 is $G = \frac{3n}{3n - 1}$, where n is number of transmitting nodes.

Proof. The aggregated throughput in a Bluetooth network is found by

$$\text{throughput} = \frac{\text{bytes transferred}}{\text{time used in seconds}}$$

$$\text{throughput} = \frac{\text{bytes transferred}}{\text{number of timeslots used} \times \text{time per timeslot}}$$

If the throughput in two different scenarios is to be compared, and the amount of data transferred is equal in the two scenarios. I.e. $\text{bytes transferred}_A = \text{bytes transferred}_B$. The aggregated throughput gain is found by

$$\text{gain} = \frac{\frac{\text{bytes transferred}}{\text{A number of timeslots used}}}{\text{A time per timeslot}}$$

bytes transferred

Based on this it is possible to find the aggregated throughput gain by counting the number of time slots used in the two scenarios to transfer a given amount of data.

The aggregated throughput gain G node using DNCBP-DH3 is:

$$G = \frac{2 \cdot 3n}{6n \cdot 2} = \frac{3n}{3n \cdot 1}$$

□

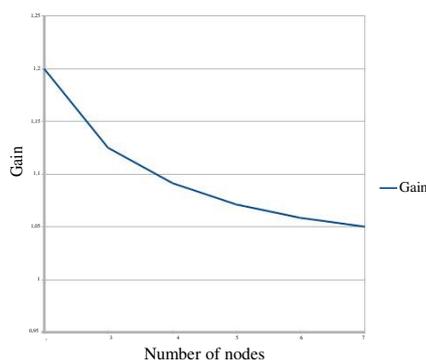
Theorem 2. The average throughput gain, G , using DNCBP-DH5 is $G = \frac{5n}{5n \cdot 2}$, where n is number of transmitting nodes.

Proof. By following the same argument as in theorem 1 the number of time slots required to transmit a DH5 packet from all source nodes are $5n + 5(n-1) + 1 = 10n - 4$. And the number of time slots required to transfer the same amount of data is $2 \cdot 5n$. The gain G in average capacity per node using network coding and DH5 packet is:

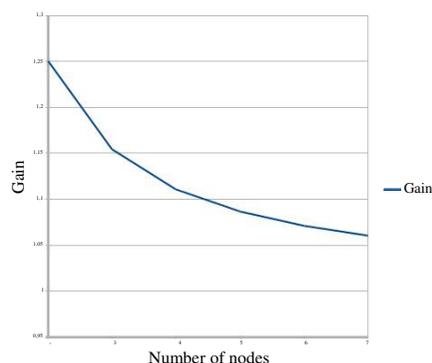
$$G = \frac{2 \cdot 5n}{10n \cdot 4} = \frac{5n}{5n \cdot 2}$$

Figure 8, 8(a), and 5.8(b) shows the gain in a piconet using network coding with DH3 and DH5 accordingly. The result is also presented in Table 1.

In a piconet with 6 slave nodes transmitting data, the gain using DNCBP-DH3 is 5.9% and 7.1% using DNCBP-DH5. Thus the throughput in a Bluetooth piconet is improved by using network coding.



(a) 3DH Async mode



(b) 5DH Async mode

Figure 8: Gain by using network coding Bluetooth

	Number of transmitting slave nodes					
	2	3	4	5	6	7
DH3	1,200	1,125	1,091	1,071	1,059	1,050
DH5	1,250	1,154	1,111	1,087	1,071	1,061

Table 1: The gain using deterministic network coding in a Bluetooth piconet

4.1.Reduced energy consumption using network coding

Previously it has been shown how the amount of data transferred from the master node is reduced, still maintaining the same amount of information. The time a Bluetooth device is transmitting is dependent of the amount of data. Consequently, a reduced amount of data will reduce the time a master is transmitting. Reduced transmitting time will reduce the energy consumption of a Bluetooth node. As shown in Figure 7 the slave nodes do not reduce their amount of data, and therefore will not reduce their power consumption.

4.2 Throughput improvement in a scatternet using network coding

Is it possible to improve the throughput in a scatternet using network coding? This section will discuss this question, based on the discussion on piconet. Assume four bidirectional unicast in a scatternet as shown in Figure 9.

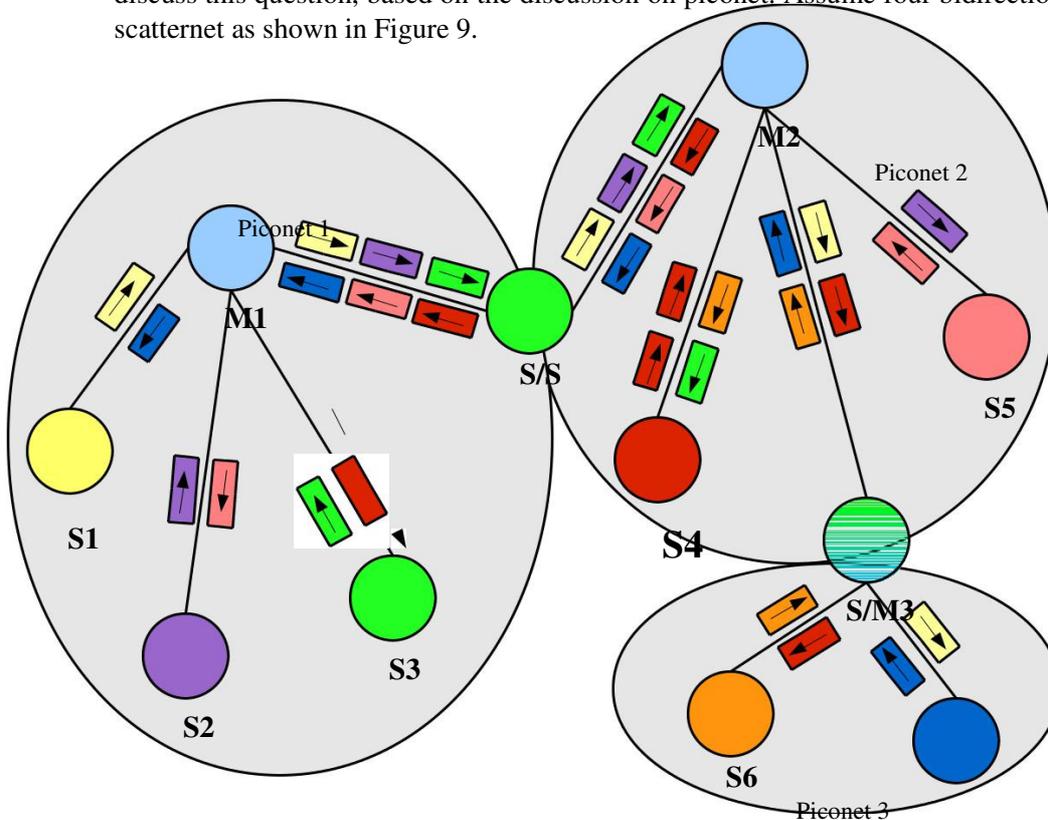


Figure 9: A scatternet with four bidirectional unicast

In this situation the gateway node between piconet 1 and piconet 2 is a slave-slave node. As a slave is not able to communicate directly to any other slave node, the gateway has to forward all the traffic between the piconets through the master nodes on both piconets. Thus, it is possible to benefit from applying network coding on the link to a slave-slave node.

The Figure .9 includes also a situation of a master-slave gateway. The links between the master-slave gateway and the M2 node transfer traffic to and from both S6 and S7. In piconet 2 the M3 is a slave, and it is possible to apply network coding on the traffic from M2 to the slave (and M3) in the piconet.

5. Implementation of network coding in a Bluetooth network

Based on the discussion above network coding could be implemented in a Bluetooth network under the following conditions:

- From the master node to the slaves in a piconet

- From the master node to the slave gateway node in a scatternet

Additionally, a possible use of network coding is from one or multiple nodes in a scatter-net broadcast or multicasting messages. As the scatternet is highly mobile, it is likely that random coding is the preferred choice.

5.1 Network coding approach

As described previously there are two different approaches for network coding, namely deterministic and random linear encoding. Deterministic linear encoding is preferred when the network topology is known. The random linear encoding is preferred when the network topology is not known or the network is frequently changing. That is, nodes may join or leave the network or the routing is changed over time. The latter situation is the case in an ad hoc network. By its nature a mobile ad hoc network changes the topology frequently. Thus, it would be inefficient using a deterministic code. A central node

would have to generate the coding coefficient every time the topology changes. In addition, the node responsible for generation of the coefficient could be detached from whole or major parts of the network. This encourages the use of random network coding.

Despite a Bluetooth piconet is ad hoc by nature, the proposed use of network coding is applied on link level. The master is the central node knowing the topology in the network, in this case the piconet. This encourages the use of deterministic linear encoding. Furthermore it is possible to determine

and use static coding coefficient, because the topology is always a star with a central node. A drawback of using deterministic network coding is the lack of erroneous protection of the data. If an error occurs, the receiver is not able to receive all packets in a generation. As a result, it is not able to decode all or some of the packets. Random network coding

5.2. IMPLEMENTATION OF NETWORK CODING IN A BLUETOOTH NETWORK

The coding would add complexity, and require more computational power and memory the nodes. This encourages the use of deterministic codes if possible.

However, applying network coding on broadcast traffic from one or multiple sources in a scatternet will require random linear encoding as:

1. There is no central node holding information about the topology

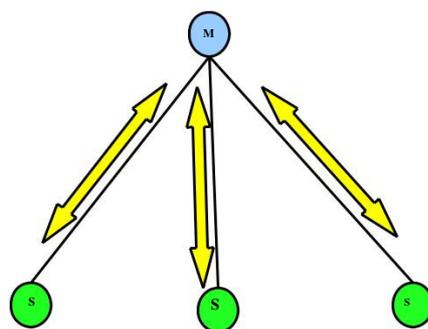


Figure 10: Two ways Master-slave communication

maximum of seven slaves.

2. Nodes leave and join the network
3. Routing is changed as the nodes moves

The rest of this work will focus on the piconet situation.

Assuming a configuration as Figure 3 consisting of eight unidirectional or four bidirectional communication streams. The maximum number of bidirectional communication links between any two slaves in a piconet is $\frac{n(n-1)}{2}$, where n is the number of slaves. If $n = 7$ i.e. the piconet is full, the maximum number of bidirectional communications between any two slave is 21.

Cycles
 The piconet can not contain cycles as the proposed protocol

include only network coding on a single link.
 Alphabet size

Using a binary alphabet is preferred due to a simpler implementation. A B in the binary field, is simple bitwise XOR. Vermani states that the only binary MDS code is the trivial codes. These are the $[n; 1; n]$, $[n; n-1; 2]$ and $[n; n; 1]$ codes. We

are therefore looking for a $[n; n-1; 2]$ code, which is a parity-check code with one parity check bit. And in the example of $n = 4$, the code is a $[4; 3; 2]$ code. Such code exists in the finite field F_2 , and one such code is the parity check code, shown here by its transposed generator matrix:

$$\begin{matrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 1 & 1 \end{matrix}$$

The encoding is possible to realize in the binary field using a trivial MDS code - the parity check code, and still keep full rank. Thus $GF(2)$ is sufficient alphabet size.

Encoding

The encoding required in the proposed DNCBP protocol can be performed as listed below. Where the left most matrix is the situation with two slave nodes communicating bidirectional.

This situation is a simple XOR of the two packets. The next matrix is used to encode in the situation where three nodes are communicating. Obviously it is not possible to communicate in pair with three nodes. Thus this situation requires one of the nodes to broadcast the same message to both of the other nodes. The third matrix is the situation where four nodes are communicating bidirectional pair wise.

$$\begin{matrix} | & m & | & m & m & | & m & m & m \\ \hline & 1 & & 1 & 2 & & 1 & 2 & 3 \end{matrix}$$

$$\begin{array}{c}
 a \mid 1 \quad a \mid 1 \quad 0 \quad a \mid 1 \quad 0 \quad 0 \\
 b \mid 1 \quad b \mid 0 \quad 1 \quad b \mid 0 \quad 1 \quad 0 \\
 \quad \quad c \mid 1 \quad 1 \quad c \mid 0 \quad 0 \quad 1 \\
 \quad \quad \quad \quad \quad \quad \quad \quad d \mid 1 \quad 1 \quad 1
 \end{array}$$

The matrix can be extended up to the general form

$$\begin{array}{cccc}
 1 & 0 & \dots & 0 \\
 0 & 1 & \dots & 0 \\
 0 & 0 & \dots & 1 \\
 1 & 1 & \dots & 1
 \end{array}$$

where the rows are the original messages, and the columns are the combined packets. Packet lengths. When encoding data, the combined data have to be of equal length. The shorter packets are padded with 0s to become as long as the longest packets. The padding is proposed done by the master during the encoding and not by the slave before transmitting. E.g. a slave transmitting a packet of 100 bytes, would only transmit the header and the 100 bytes. If the slave did pad the data up to 339 bytes, the power consumption would triple for that packet. Therefore the proposed protocol is to have the master pad data as necessary.

Security considerations

The proposed application of network coding in a Bluetooth network will enable all nodes to read all traffic in the piconet. In

a piconet without network coding a slave is only receiving traffic destined by itself. However, there are recent presentation e.g. at the hmocon 2009 [24] and interview at the Revision3 Internet Television ,showing that sniffing of Bluetooth network is not only reserved for expensive commercial sniffing tools. An article by Max Moser gives an overview on how to turn a Bluetooth dongle into a sniffer.

Based on this security measures should be in place to maintain confidentiality between nodes in a piconet both when using network coding and not if confidentiality is important. There are applications (e.g. P2P file sharing and information board) where the information is supposed to be shared between the nodes in the network.

However, in this case integrity of the messages could be an issue.

5.3 Possible application

The proposed protocol could be used to improve performance in respect of throughput and power reduction for a pair of nodes communicating. However, as all nodes are able to read information destined to the other nodes it is possible to use the same protocols in other application as well. This could be e.g. message board, and P2P file sharing.

6. Conclusion

This thesis is discussing a possible application of network coding in Bluetooth network. Due to the time division duplex (TDD) used in Bluetooth network there are several constraints to take into account, compared to other wireless network protocols like wireless LAN (WLAN). One of them is that the slave node is not able to communicate directly with other slave nodes, but rather is required to communicate through a master node. A protocol for applying network coding in Bluetooth piconet has been proposed. The proposed protocol is using deterministic network

coding to combine packets from the slaves at the master node. The master node forwards the combined packets to all slaves. It is required to transmit $n+1$ packets, where n is the number of source nodes. An encoding equation using a MDS code in the binary field is proposed. Encoding in the binary field makes the operation computationally easy. Furthermore, the proposed equation scales easily to the maximum number of nodes in a piconet. The encoding and decoding is performed using simple bitwise XOR of the packets, without need to store neither encoding matrices, nor look-up tables. This is an advantage particular for nodes with limited computational power and memory.

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